

Ensemble Data Assimilation in CESM/POP and CAM

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nstitute for	Mathematics	Applied to	Geosciences
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1. Overview	3. Atmosphere	5. Ocean	6. World Ocean Database (2005) Observation Counts for 1998 and 1999
The Data Assimilation Research Testbed has been combined	The atmospheric assimilation started with 1998 and will con-	The large ensemble and diverse atmospheric forcing lead to	

with the Community Atmosphere Model (CAM) version 4 and the Parallel Ocean Program (POP) to create loosely coupled ensemble analyses of the ocean that are consistent with the analyses of the atmosphere. There is no communication from the updated ocean states to the atmosphere. A fully-coupled system is planned. The performance of the assimilation is assessed by comparing the short-term forecast state to the observations about to be assimilated: a metric that is not dependent on a third party analysis. DART has a wide range of observation-space diagnostic tools to evaluate the performance of the assimilation.

1.1 Atmospheric Assimilations

- CAM Version 4: will be used for the next IPCC • 80 ensemble members
- $(1.9^\circ \times 2.5^\circ)$ 96 latitudes, 144 longitudes, 26 levels
- variables influenced by the assimilation: surface pressure, temperature, horizontal winds, specific humidity, cloud liquid, and cloud ice
- assimilation performed every 6 hours starting 1 Dec 1997 • all observations used in the NCEP/NCAR reanalysis. Globally, about 100,000 observations every 6 hours • all members are forced by the same ocean analyses • adaptive Inflation used to maintain ensemble spread

1.2 Oceanic Assimilations

tinue to the present. The 80 member ensemble is capable of quantifying uncertainty and model performance over a period when the atmosphere is very well observed; providing an excellent means of estimating variability in the presence of uncertainty.



Figure 2: Contours of the 500hPa geopotential height in 40 of the 80 CAM members for 6 hour forecasts valid 12:00 UTC 17 February 2003 (left) and 06:00 UTC 1 July 2001 (right). All of the model states are consistent with the observations, the ensemble captures the uncertainty in the system.



improvements in some aspects of the ensemble mean ocean analysis; our focus is the 24hour forecast of the ensemble when compared to observations.



Figure 5: Two-year estimate of the velocity at approx 300m shows a significantly improved North Atlantic Current path in the assimilation (right) compared to a POP free run (left). The current is much tighter and follows the coast much more closely, something free runs fail to do. These results were from the DARTPOP23 experiment.





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7. More Observation-Space Diagnostics

DART has many more diagnostics than those shown rank histograms, 3D of the plots here; observation locations color-coded to the observation value/QC value/rmse/bias/spread/rejected observations, mapping tools, ...

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	238	340.0700	61.0000	300	8.6230	8.8421	0	615	7.2976e+05	2
	239	340.0700	61.0000	400	7.0700	8.6502	0	616	7.2976e+05	2
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1.2.1 **DARTPOP48**

• 1 degree grid with displaced pole, 60 levels (POP gx1v6) • 48 members initially drawn from a model climatology • prescribed sea ice concentration

 assimilate every midnight starting 3 January 1998 • use all temperature and salinity obs in the World Ocean Database in a +/-12 hour window

• atmospheric forcing for each POP member comes from a unique CAM ensemble member analysis

1.2.2 DARTPOP23 differed in that:

 23 members initially drawn from a model climatology • each member has identical observed atmospheric forcing

2. DART: Assimilation Schematic



Figure 3: The RMSE and spread of the 6 hour forecasts of the U winds compared to radiosonde observations for the month of February, 2003 \approx 5 years into the assimilation. The totalspread (the square root of the pooled ensemble variance and the observation error variance) remains fairly steady in both hemispheres. Similar plots for vertical profiles are also standard with DART.

4. Atmospheric Observations used with DART

DART supports a wide variety of observations. The design paradigm for DART means that once an observation type is supported, all relevant models that work with DART can assimilate those same observations. The following table simply lists those used for this experiment. There are many more supported by DART; GPS Radio Occultations, for example.

Figure 6: The difference between the Hadley OI SST and various POP experiments. The top-left panel is a fully coupled 20th century run. The top-right panel is an ocean-ice hindcast simulation. The top two panels do not use DART. Both DART results (bottom panels) show a dramatically improved fit to the Hadley product.

The following figures have multiple axes. The solid lines depict the RMSE or spread and use the left axis. The unconnected symbols depict the number of observations used and the number possible using the scale on the right; their difference is the number rejected by the assimilation.



Figure 7: The error in the XBT temperatures in the Atlantic (left) are about the same, even though (in general) fewer observations were rejected by the assimilation system for the DARTPOP48 experiment. The ensemble spread (right) shows improvement as a result of using the ensemble of CAM atmospheric forcing fields.



Figure 10: DART's diagnostic tools make it easy to explore what observations are being rejected, and why. This is an example of some XBT observations in the North Atlantic. The information in the plots is linked, selecting observations in one view highlights them in all the views.

8. For further information

Our DART site is: http://www.image.ucar.edu/DAReS/DART There you will find information about how to download the latest revision of DART from our subversion server, information on a full DART tutorial (included with the distribution), and contact information for the DART development group.





Figure 1: Illustration for a toy ensemble size of 3.

The DART system allows direct comparison of the forecast model state to the observations as part of the assimilation algorithm at virtually no additional expense. All performance metrics are relative to the observations, *i.e.* at step 4 of Figure 1. Observations that are too far away from the prior ensemble mean are not used in the assimilation or the performance metrics. It is possible to achieve a low RMSE by rejecting all the observations that do not agree with the ensemble, so the number of observations rejected must be considered. Not all observations *should* be used, however!





Figure 8: The DARTPOP48 moored temperatures in the Pacific exhibit a systematic decrease in error (left) while maintaining a larger ensemble spread (right).

Please see companion poster in this session: Transient ocean features resulting from the initialization of an ocean ensemble assimilation system.

References

[DART 09] J. Anderson, T. Hoar, K. Raeder, H. Liu, N. Collins, R. Torn, and A. Arellano, 2009: The Data Assimilation Research Testbed: A Community Data Assimilation Facility. *BAMS* **90** No. 9 pp. 1283–1296

The National Center for Atmospheric Research is sponsored by the National Science Foundation.



WCRP Open Science Conference, 24-28 October 2011, Denver, Colorado, USA