Atmospheric Motion Vector (AMV) Algorithm

Generating a Polar Wind Vector Data Set from METOP-AVHRR Observations

Roger Huckle^{1,2}, Jörg Schulz¹

¹ EUMETSAT, Eumetsat-Allee 1, 64295 Darmstadt, Germany

² VEGA Space GmbH, Europaplatz 5, 64293 Darmstadt, Germany

· Displacement of objects from one satellite image to the next

Objects can be clouds, water vapor or other trace gases

AMVs are filtered applying several quality checks

• EUMETSAT algorithm uses full spatial resolution Local Area Coverage (LAC) data

Objects are identified in the base image and searched for in the next image(s)

Needs a minimum of two images; three or four images likely to increase the quality

• For AVHRR only the IR-Window images from channel 4 (11µm) are used

Overpasses in Polar Regions are 102 minutes apart, but still usable [1]

2 (duplet orbits)

3 minute PDUs

From 55° pole wards

For geostationary satellites images every 15-30 minutes are used

• NWP wind field can be used to define a search area and to reduce computation time

The ERA-CLIM Project

- Aim: Prepare the observations for a 20th century reanalysis
- Project Lead by ECMWF [2]
- EUMETSATs Contribution:
 - · AVHRR Atmospheric Motion Vectors · Radio Occultation bending angles
 - ASCAT Level 1 data products
 - Combined GOME-2 & IASI ozone columns
 - · METEOSAT Atmospheric Motion Vectors as well as
 - Clear and All Sky Radiance.

The Opportunity

- Two algorithms for AMV retrieval from METOP-A AVHRR are implemented:
- · Operational as in EUMETSAT ground segment [3]
- EUMETSAT prototype based on CIMSS algorithm [4] Creation of extensive data set (2007-2012) using
- both algorithms for the Metop-A mission. Comparison against radiosondes and NWP data.
- Unique opportunity to directly compare the two different algorithms over more than 5 years.

In the EUMETSAT ground segment 3 minute pieces from an orbit (PDU) are used. AREA files are in McIDAS file format and contain channel 4 data in a polar stereographic projection (one for each pole).

EUMETSAT (Operational)

¹CIMMS = Cooperative Institute for Meteorological Satellite Studies

and Statistics Comparisons

Number of images

Area covered

Input data



Direction and speed distribution of mid level (700-400 hPa) winds over Antarctica for the operational (left) and CIMSS (right) algorithm.



Typical wind speed distribution for the operational (left) and CIMSS (right) algorithm for one day.

Conclusions & Discussion

- · Comparison of two algorithms for more than 5 years after completing reprocessing campaign provides high potential for quality analysis and algorithm improvement;
- · Preliminary results on selected test cases:
 - More winds detected by the prototype;
 - Operational alg. winds also further away from pole; - Distribution of wind directions similar, but higher
 - wind speeds in EUMETSAT operational winds; -QI distribution in CIMSS data Gaussian, with peak at 50%:
 - -QI maximum for ops near 0% and second maximum for OI > 80%
 - Comparison statistics vs. ECMWF forecast data for one day show slightly better results for CIMSS winds
- · Possible reasons for algorithm quality differences: - Use of duplets instead of triplets may lead to less
 - good temporal consistency of derived winds; - Height adjustment of CIMSS winds tuned with
 - objective analysis towards a better fit with forecast data leads to better match with validation data



Location of AMVs for the operational (left) and CIMSS (right) algorithm. More winds away from the pole in the operational algorithm due to duplet mode.



Preliminary wind speed comparison vs. ECMWF forecast data (operational (left) and CIMSS (right)), for one day at 12 UTC.

		Operational			Prototype		
	Speed	U-comp	V-comp	Speed	U-comp	V-comp	
Bias	0.34	0.78	1.31	0.76	0.62	0.20	
RMS	5.13	5.62	5.94	4.07	4.17	4.35	

AMV speed, u and v component compared vs. ECMWF

Outlook

- Consistently processed Metop-A polar AMVs will become available from EUMETSAT towards the end of 2012;
- · Plan to compare geostationary with polar winds in overlapping area to further assess need for duplet orbit approach:
- Plan to generate AMVs with EUM operational algorithm using AVHRR GAC data back to 1982.

The Authors



Huckle

Schulz



	Quality Indicators	EUM	CIMSS
0	Forecast Consistency	1.0	0.0
-	Spatial vector consistency (Buddy)	2.0	2.0
	Spatial height consistency	0.0	N/A
	Temporal height consistency	0.0	N/A
	Tracking vector consistency	2.0	1.0
	Tracking speed consistency	0.0	1.0
	Tracking direction consistency	0.0	1.0
	U-component	N/A	0.0
	V-component	N/A	0.0

3 (triplet orbits)

AREA files

From 65° pole wards

CIMSS¹ (Prototype)

Quality Indicators for every AMV [5]. With current weighting for the overall QI. Overall QI also available excluding forecast QI. Ol distribution - 20080412





40 50 QI value Overall QI distribution for the two algorithms. The higher the value the "better" the AMV.

References

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forecast data (within 1 hour). All values in ms-1.